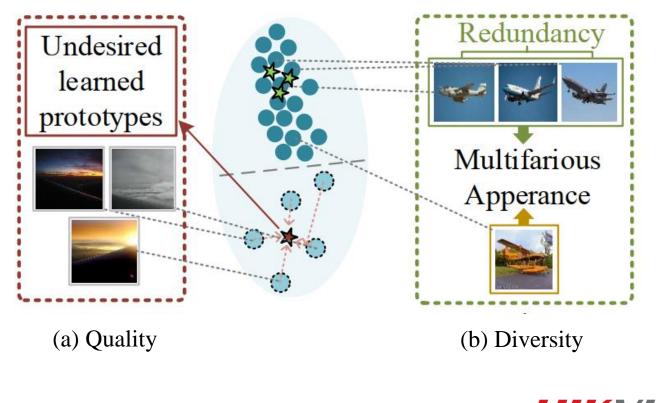
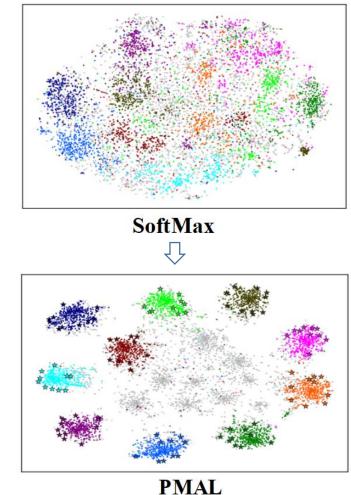
#### **PMAL: Open Set Recognition via Robust Prototype Mining**

• Problems of learning protoypes in OSR

●High quality sample ●Low quality sample ☆ Prototype



Effect Visualization



Contact E-mail: lujing6@hikvision.com Jing Lu

TinyImageNet

#### **PMAL: Open Set Recognition via Robust Prototype Mining**

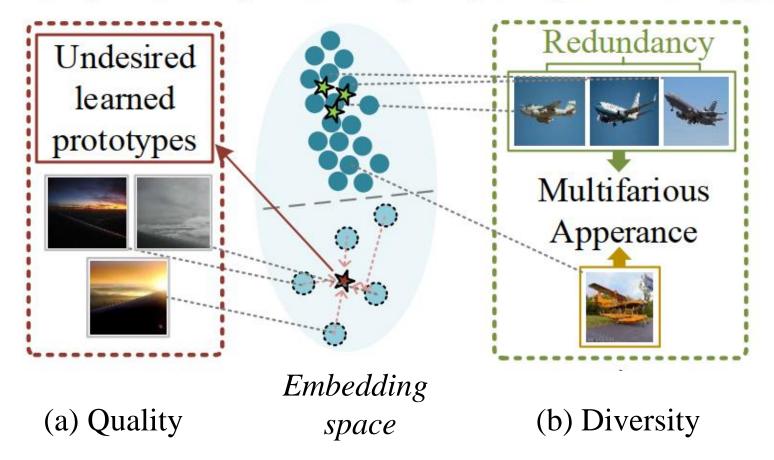
Jing Lu<sup>1\*</sup>, Yunlu Xu<sup>1\*</sup>, Hao Li<sup>1</sup>, Zhanzhan Cheng<sup>1,2†</sup>, Yi Niu<sup>1</sup>

<sup>1</sup> Hikvision Research Institution, Hangzhou, China <sup>2</sup> Zhejiang University, Hangzhou, China {lujing6, xuyunlu, lihao50, chengzhanzhan, niuyi}@hikvision.com

#### **Problems**

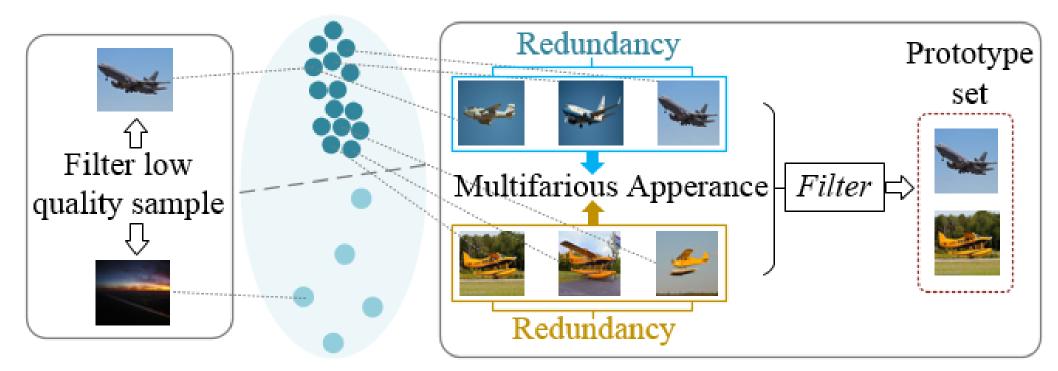
• Implicit Learned Prototypes

●High quality sample ●Low quality sample ☆ Prototype



#### Motivation

• *Explicit* Prototype Mining: PMAL

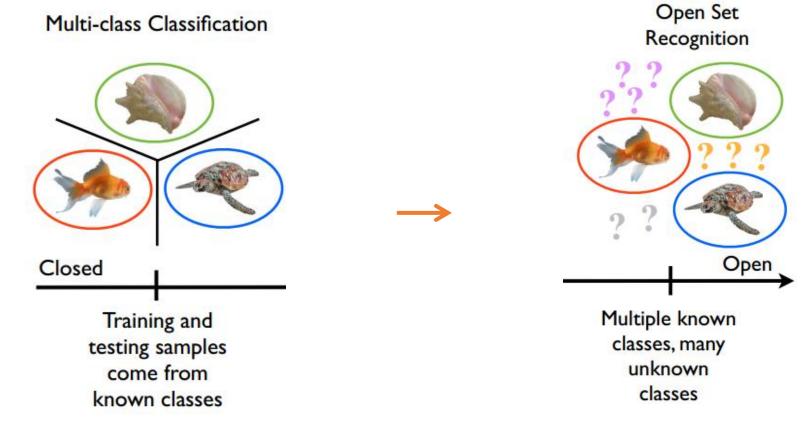


(a) *Mine High-quality Candidates* 

(b) Filter with diversity

#### Preliminary

• Open Set Recognition(OSR)



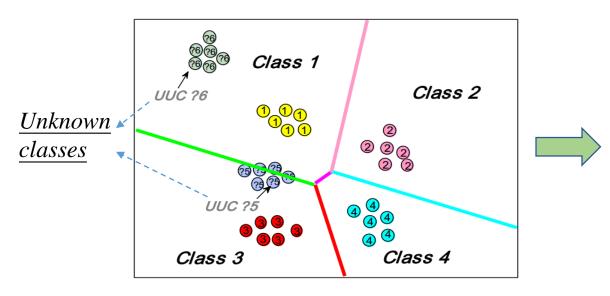
Ideal: Close Set Assumption

• Actually: Open Set Environment

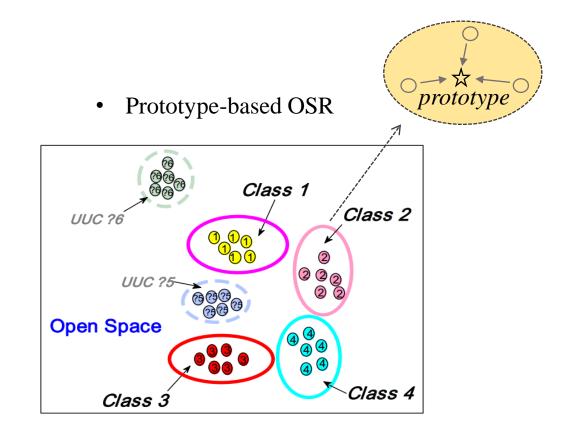
Scheirer, W. J., et al. 2013. Towards Open Set Recognition. TPAMI.

# Preliminary

- Prototype-based OSR
  - Softmax-based close-set recognition



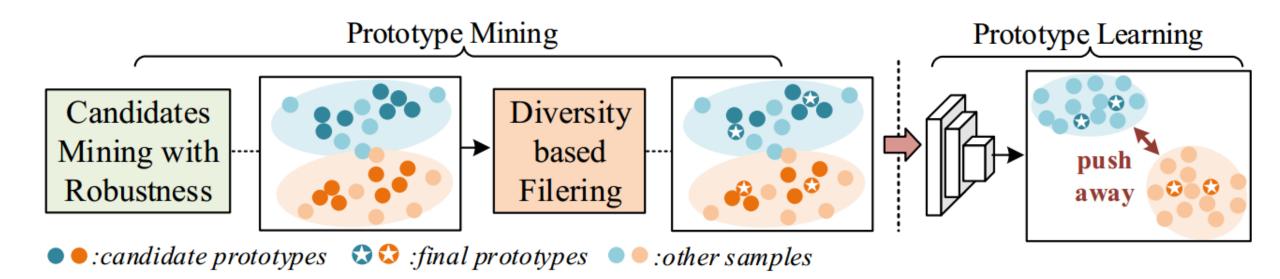
✓ Unable to tell UNKNOWN classes



- ✓ Learn compact intra-class embedding
- ✓ Reserve more space for UNKNOWN classes

Jaderberg, M, et al. 2015. Spatial Transformer Networks. NeurIPS.

• Overview of PMAL



Mine *high-quality* samples as prototype candidates  $\bullet$ 

High-quality samples satisfy<sup>[2]</sup>: □ Data uncertainty modelling<sup>[1]</sup> Equal 1:  $z(x_i) = \phi(x_i) + n(x_i), \ n(x_i) \sim \mathcal{N}(0, \sigma(x_i)) \quad \Box >$  $z_i \approx \phi_i$  $\Box$  For a high-quality samples  $x_i$ **•** Key properties of high-quality samples Equal 2:  $d_{\mathcal{M}}(\phi_i^1, \phi_j^1) \approx d_{\mathcal{M}}(\phi_i^2, \phi_j^2)$ Embedding Mahalanobis distance space  $Z^{l}$ **D** Embedding Topology Equal 3:  $t(z_i) \triangleq (d_{\mathcal{M}}(z_i, z_1), ..., d_{\mathcal{M}}(z_i, z_N))$ Embedding **D** Embedding Topology robustness space  $Z^2$ Equa. 4:  $r(x_i) \triangleq exp(-||t(z_i^1) - t(z_i^2)||_2)$ 

(a)

- Mine *high-quality* samples as prototype candidates
  - ✓ Data uncertainty modelling<sup>[1]</sup>

Equal 1:  $z(x_i) = \phi(x_i) + n(x_i), \ n(x_i) \sim \mathcal{N}(0, \sigma(x_i)) \quad \Box >$ 

✓ Key properties of high-quality samples

Equa. 2:

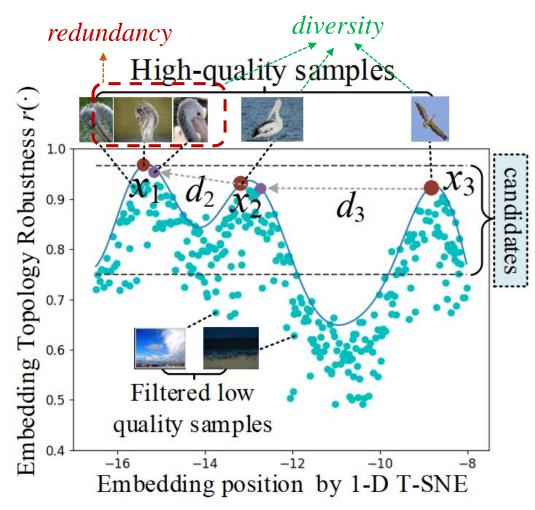
Mahalanobis distance

✓ Embedding Topology robustness Equa. 3:  $t(z_i) \triangleq (d_{\mathcal{M}}(z_i, z_1), ..., d_{\mathcal{M}}(z_i, z_N))$ Equa. 4:  $r(x_i) \triangleq exp(-||t(z_i^1) - t(z_i^2)||_2)$ 

 $d_{\mathcal{M}}(\phi_i^1,\phi_j^1) \approx d_{\mathcal{M}}(\phi_i^2,\phi_j^2)$ 

High-quality samples satisfy<sup>[2]</sup>:  $z_i \approx \phi_i$  $\Box$  For a low-quality samples  $x_i$ Embedding space  $Z^{I}$ Embedding space  $Z^2$ (b)

• Filter with diversity



# Local maximum robustnessLarge embedding distance

• Greedy filtering algorithm

 $P_{k} = \bigcup_{i=1}^{T} \{ x_{i} | \max_{x_{i} \in C_{k}} \{ \min_{x_{j} \in C_{k}} d_{\mathcal{M}}(z_{i}, z_{j}) | r(x_{j}) > r(x_{i}) \} \}$ 

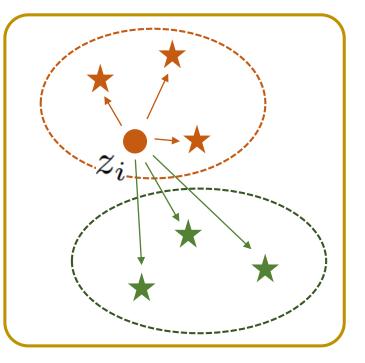
 $C_k$ : candidate set of class k

 $P_k$ : final prototype set of class k

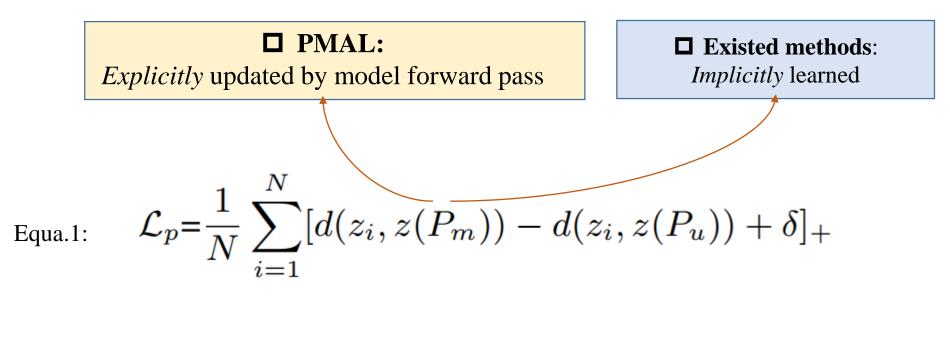
- Embedding optimization
  - ✓ Point to Set distance

$$z_i \xrightarrow{query} z(P_k) = (z(p_{k,1}), ..., z(p_{k,T})) \in \mathbb{R}^{D \times T}$$

Equa.1: 
$$z_i^{att}(P_k) = SoftMax(\frac{z_i^{\mathrm{T}} z(P_k)}{\sqrt{d}}) z(P_k)$$
  
 $\bigcirc$   
Equa.2:  $d(z_i, z(P_k)) = 1 - \frac{z_i^{\mathrm{T}} z_i^{att}(P_k)}{|z_i^{\mathrm{T}}||z_i^{att}(P_k)|}$ 



• Embedding optimization



Equa.2: 
$$P_u = \underset{P_k \in P \setminus P_m}{\operatorname{arg\,min}} \left( d(z_i, z(P_k)) \right)$$

## Ablation

• Each component

Table 3: Ablations of each module on TinyImageNet.										
С	omponents	(a)	(b)	(c)	(d)	(e)	(f)			
PM	High-Quality	$\checkmark$	1	$\checkmark$		$\checkmark$	$\checkmark$			
I IVI	Diversity		$\checkmark$		$\checkmark$	$\checkmark$	$\checkmark$			
EO	Point-to-Set		1	$\checkmark$	$\checkmark$		$\checkmark$			
	AUROC	80.3	78.1	81.6	80.2	81.9	83.1			

- Both high quality and diversity matters for prototypes.
- Point-to-set distance helps learning better embedding space.

### Ablation

• Each component

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С	components	(a)	(b)	(c)	(d)	(e)	(f)
PM	High-Quality	$\checkmark$		$\checkmark$		$\checkmark$	$\checkmark$
	Diversity		$\checkmark$		$\checkmark$	$\checkmark$	$\checkmark$
EO	Point-to-Set			$\checkmark$	$\checkmark$		$\checkmark$
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						·/	×

Table 3: Ablations of each module on TinyImageNet.

- Both high quality and diversity matters for prototypes. ٠
- Point-to-set distance helps learning better embedding space. ٠

### Ablation

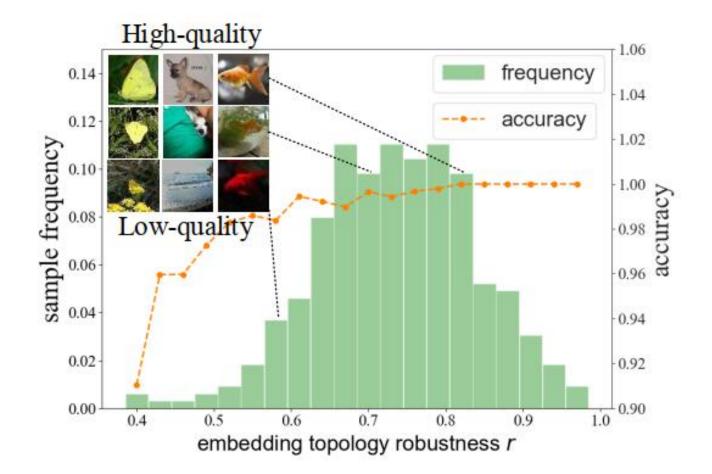
• Replace components in PM with existed strategies

Table 4: Comparisons with other methods on the *quality* and *diversity* property.

		Method	ACC	AUROC
Mine Hick quality	Г	(a)Probability	81.9	79.3
Mine High-quality Candidates	4	(b)Deep Ensembles	82.3	80.5
Cunatuates	L	(c)MC-dropout	81.6	78.8
Diversity	Г	(a)Randomization	81.5	79.1
filtering	1	(b)Clustering	81.8	79.6
v O		Ours	<b>84.7</b>	83.1

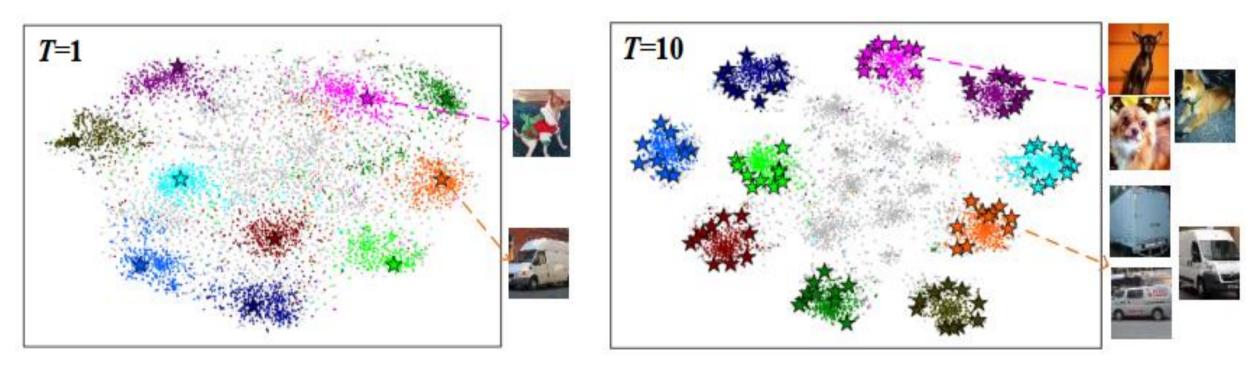
### Visualization

• High quality



# Visualization

• Diversity

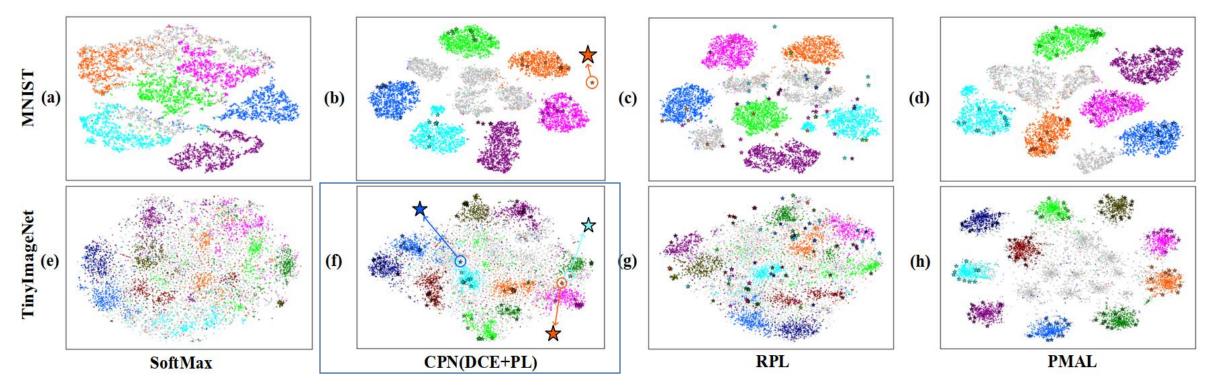


✓ Multifarious prototypes

# Visualization

• Embedding space

#### Each color denotes different classes and 'gray' denotes unknowns



- On *simple* MNIST, all prototype-based methods performs satisfying.
- On more *complex* TinyImageNet, PMAL performs much better.

#### Performance

• Mainstream small-scale benchmarks

Table 1: Close set ACC and Open set AUROC on small datasets. '\*' denotes implemented results and 'C' is short for 'CIFAR'.

Methods			Close set	t ACC			Open set AUROC					
Wiethous	MNIST	SVHN	C10	C+10	C+50	TINY	MNIST	SVHN	C10	C+10	C+50	TINY
SoftMax	99.5	94.7	80.1	-	-	-	97.8	88.6	67.7	81.6	80.5	57.7
CPN (Yang et al.)	99.7	96.7	92.9	94.8*	95.0*	81.4*	99.0	92.6	82.8	88.1	87.9	63.9
PROSER (Zhou, Ye, and Zhan)	-	96.5	92.8	-	-	52.1	94.3	-	89.1	96.0	95.3	69.3
CGDL (Sun et al.)	99.6	94.2	91.2	-	-	-	99.4	93.5	90.3	95.9	95.0	76.2
OpenHybrid (Zhang et al.)	94.7	92.9	86.8	-	-	-	99.5	94.7	95.0	96.2	95.5	79.3
RPL-OSCRI (Chen et al.)	99.5*	95.3*	94.3*	94.6*	94.7*	81.3*	99.3	95.1	86.1	85.6	85.0	70.2
ARPL (Chen et al.)	99.5	94.3	87.9	94.7	92.9	65.9	99.7	96.7	91.0	97.1	95.1	78.2
RPL-WRN (Chen et al.)	99.6*	95.8*	_95.1*_	95.5*	<u>95.9*</u>	81.7*	99.6	96.8	90.1	97.6	96.8	80.9
PMAL-OSCRI	99.6	96.5	96.3	96.4	96.9	84.4	99.5	96.3	94.6	96.0	94.3	81.8
PMAL-WRN	<b>99.8</b>	97.1	97.5	<b>97.8</b>	<b>98.1</b>	<b>84.7</b>	<b>99.7</b>	97.0	95.1	<b>97.8</b>	96.9	83.1
	/											

#### Performance

• Mainstream small-scale benchmarks

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CGDL (Sun et al.)	99.6	94.2	91.2	-	-	-	99.4	93.5	90.3	95.9	95.0	76.2
OpenHybrid (Zhang et al.)	94.7	92.9	86.8	-	-	-	99.5	94.7	95.0	96.2	95.5	79.3
RPL-OSCRI (Chen et al.)	99.5*	95.3*	94.3*	94.6*	94.7*	81.3*	99.3	95.1	86.1	85.6	85.0	70.2
ARPL (Chen et al.)	99.5	94.3	87.9	94.7	92.9	65.9	99.7	96.7	91.0	97.1	95.1	78.2
RPL-WRN (Chen et al.)	99.6*	95.8*	95.1*	95.5*	95.9*	81.7*	99.6	96.8	90.1	97.6	96.8	80.9
PMAL-OSCRI	99.6	96.5	96.3	96.4	96.9	84.4	99.5	96.3	94.6	96.0	94.3	81.8
PMAL-WRN	<b>99.8</b>	<b>97.1</b>	97.5	<b>97.8</b>	<b>98.1</b>	84.7	99.7	97.0	95.1	<b>97.8</b>	96.9	83.1

#### Performance

• More large-scale benchmarks

Table 2: Comparisons on 3 large-scale datasets. We denote 'ImageNet' as 'IN' for simplicity.

Method	C	lose Set A	CC	Ope	en Set AUI	ROC	Additional Params			
Methou	IN-LT	IN-100	IN-200	IN-LT	IN-100	IN-200	IN-LT	IN-100	IN-200	
Softmax	37.8	81.7	79.7	53.3	79.7	78.4	0	0	0	
CPN	37.1	86.1	82.1	54.5	82.3	79.5	2M	0.2M	0.4M	
RPL	39.0	81.8*	80.7*	55.1	81.2*	80.2*	2M	0.2M	0.4M	
RPL++	39.7	-	-	55.2	-	-	4M	-	-	
PMAL	42.9	86.2	84.1	71.7	94.9	93.9	0	0	0	

✓ More obvious advantages on complicated scenarios

#### **Contact Information**





#### PMAL: Open Set Recognition via Robust Prototype Mining

Contact E-mail: <u>lujing6@hikvision.com</u> Jing Lu



Our Team Homepage: https://davar-lab.github.io/